Analysis of Polynomial Functions with the TI-59 Calculator

Part 1

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Between the elementary functions accessible by direct calculation and higher-order equations reserved for the computer, there exists an intermediate domain where programmable calculators are useful.

Certain concrete problems sometimes lead to such equations without this creating an exceptional volume of calculation. Some have been encountered, for example, in the handling of small 6 by 6 matrices concerning medical data. Other technicians are also familiar with this type of obstacle in their fields. Consequently, the feeling is that it is worthwhile proposing a convenient program worked out on the Texas Instruments TI-59 and designed for sixth-order and lower-degree polynomial functions.

Independent of the advantages in mathematical terms, I hope that this article will give the user a meaningful introduction to this highly advanced calculator. For practical reasons, the original goals were as follows:

- calculate all the characteristic elements of the function (roots, maximums, minimums, and points of inflection where applicable)
- automatically plot the function curve
- control the program with a single key

Obtaining these conditions virtually eliminates any chance of operating error, and frees the user for other tasks once the calculation has begun. This is especially the case since the main program can be stored on a single magnetic card as can the printout program. Altogether, this provides a simplified procedure which nonetheless permits execution of the successive steps in the following

sequence:

- obtaining the appropriate boundaries of the interval to be studied
- choice of the increment
- recall of the maximum error
- calculation of roots in increasing order
- printout of correctly sampled tables of values

All of the above is applicable both for the initial polynomial and for derived polynomials. Because of the geometric significance of the derivative, these provide the maximums and minimums of the function as well as possible points of inflection.

Given that excessive automation can be inconvenient in certain cases, a manual procedure has been provided to permit using the keys to enter the lower and upper boundaries of the interval to be studied along with the value of the increment desired.

After a brief discussion of the calculation principles, the main program and then the automatic printout program for the function curve will be examined. A commentary on numerical applications will conclude the examination.

Calculation Principles

Here is the type of polynomial that will be dealt with:

$$P(x) = a_0 x^n + a_1 x^{n-1} + ... + a_n \ (a_0 \neq 0, n \leq 6)$$

where x is a real number and coefficients a_0 , a_1 , ... a_n , are known real numbers.

The method used to determine the roots of P(x) = 0 is

bipartition. This consists of successive dichotomies of the interval (a, b) chosen with the function being continuous over this interval. The calculation is performed sequentially, and the step increment is designated by $\triangle x$.

To determine the root of the equation which belongs to the segment $\triangle x$, the latter is divided in two, and the calculator retains that half at whose extremes the function has opposite signs. The new shortened segment is further divided in two, and the process is repeated iteratively until the upper value of the residual interval is limited by the error limit. The middle of this final interval represents a root of the function to within the error.

This method provides only a single value in an interval △x and requires more calculating time if boundaries a and b are taken too far apart. If they are taken too close together, the risk is obviously one of losing a root; the same applies if $\triangle x$ is too large. Therefore we attempt to eliminate these drawbacks due to too much and too little by programming Lagrange's theorem. This replaces a subjective estimation of the boundaries by a calculation guaranteeing a reliable interval (a, b).

Let $a_0 > 0$ and a_k ($k \ge 1$) be the first of the negative coefficients of the polynomial P(x). The following number as the upper limit of the positive roots of equation P(x) = 0 can then be used:

$$R = 1 + \sqrt[k]{\frac{B}{a_0}}$$

where B is the largest of the absolute values of the negative coefficients of the polynomial P(x). Now the user no longer has to distinguish the two values of x between which the roots are supposed to fall. The calculator finds and prints them. To determine the possible limit of the negative roots of the equation, use x = -z. This involves changing the sign of the coefficients of the odd registers. However, if the latter equation has no positive roots, the initial equation has no negative roots and the calculator will not provide any.

Optimization of the process is completed by another method. As soon as a root is found, it serves as the lower boundary of the cycle of the following calculation. This sets the increment interval in the new segment to be explored. The correction is aimed at improving the reliability of root detection: this is an essential point.

Observe that details of the program code depend on some of the special capabilities of the TI-59 and PC-100A printing cradle. Naturally, the reader is referred to the instruction manual for full details. In passing, it is merely my intention to mention the decisive factors in my work.

The user has 960 program statements or 100 storage locations available with the possibility of adjusting their respective size as a function of the problem. Each memory block occupies eight program statements. The standard distribution adopted uses 480 program statements and sixty data-storage locations which will be filled entirely. The micromemory connects to the calculator and provides a library of twenty-five programs totalling

Of the forty functions to which the OP key provides

access, special mention can be made of the following:

- printout of alphanumeric characters
- sign indicator
- error indicator
- incrementing and decrementing of memories
- listing of memory content
- listing of labels

Lastly, the T register is very important. Here, it is possible to store and recall a number and test it with respect to the contents of the display register.

In the final analysis, the TI-59 has the quantitative and qualitative features which prove useful in writing a program of the type that is being presented.

Main Program

Data entry:

For reasons of efficiency, the initialization sequence and data entry is not placed at the beginning of the program but at statement 066 with the LBL A instruction and statement 073 with the LBL B instruction (see listing 1). The coefficients of the polynomial are stored by conventional indirect addressing from x6 at R16 to x0 at R10 with a zero introduced when a corresponding term of a power of x is missing.

Evaluation of the polynomial:

This is the role of the LBL A' instruction placed at location 000 to save calculating time, since this sequence is called frequently.

Determination of boundaries and step increment:

The calculation is monitored by LBL C which, in particular, uses subroutines RCL and STO and PGM 08 of the Solid-State Software. After execution of the sequences the following results are given:

- the lower boundary a is printed out at location 091
- the upper boundary b is printed out at location 099
- the absolute value of the interval (b-a) is printed out at location 117
- the step increment ∆x is printed out at step 124 immediately after steps 120 thru 122 which contain the variable number of partitions of interval (a, b) or 020 in our listing

The appearance of a zero as a boundary value means the absence of roots for the interval considered, the coefficients of the polynomial being positive or zero. And by three successive calls (PGM 08 A, PGM 08 B, PGM 08 C) program C finally aligns the assignments with those of the library by storing a at Ro1, b at Ro2 and Ax at Ro3.

Program execution:

This discussion of the mathematical method used will save the trouble of describing the principles again. As for execution:

- LBL RCL (statement 133) changes the sign of the coefficients of the odd registers (R15, R13, R11)
- LBL STO (statement 155) plays a complex role. At statement 176, it stores the first coefficient which is

Listing 1: Main program listing of the polynomial-function analysis on the T1-59.

Listing 1 continued:

416 417 418 419 420	11 11 42 STD 10 10 43 PCL 12 12	436 437 438 439 440	04 4 95 = 42 STD 13 13 43 RCL	456 16 16 457 43 RCL 458 16 16 459 99 PRT 460 43 PCL	476 10 10 477 99 FRT 478 98 ADV 479 92 RTI
421 422 423 424 425 426 427 428	65 × 02 2 95 = 42 STD 11 11 43 PCL 13 13 65 ×	441 442 443 444 445 446 447 448	15 15 65 x 05 5 95 = 42 STD 14 14 43 RCL 16 16	461 15 15 462 99 PRT 463 43 RCL 464 14 14 465 99 FRT 466 43 RCL 467 13 13 468 99 PFT	001 16 A' 066 11 A 073 12 B 081 13 C 133 43 PCI 155 42 STI
429 430 431 432 433 434 435	03 3 95 = 42 STD 12 12 43 RCL 14 14 65 =	449 450 451 452 453 454 455	65 × 06 6 95 = 42 STB 15 15 00 0 42 STB	469 43 RCL 470 12 12 471 99 PRT 472 43 RCL 473 11 11 474 99 PRT 475 43 RCL	155 42 STI 283 14 D 291 15 E 323 18 C' 399 19 D' 414 17 B'

not zero in register Ro7 and recalls its rank in Ro0 to store it at STO 20.

At statements 182 thru 192, all the terms of the polynomial, starting with the first, are divided by the first coefficient which is not zero. This make ao positive and equal to 1. This operation must be kept in mind to correctly interpret the change from one polynomial to the next when reading the results.

Location of the first negative coefficient to determine its value and rank begins at statement 196 and uses two loops, statements 203 thru 205 and 207 thru 219. Finally, if the negative coefficient exists, its absolute value is stored in register Roz and its rank in register Roz, and then its relative position with respect to the first coefficient which is not zero is stored in register R_{20} . Incidentally, the register number of a coefficient (Ro1) can be determined easily by adding 9 to its ordinal number (Roo).

The calculation of the negative coefficient which has the highest absolute value starts at statement 233 and uses the T register with a relatively sophisticated process. This employs four loops, 251 thru 242, 245 thru 267, 271 thru 249 and 279 thru 249. The evaluation of R in Lagrange's formula takes place at statements 255 thru 265.

On the whole, the STO program can be considered to end with the RTN instruction of statement 218 with a long conditional branch with multiple options which operates as a subroutine and ends at the RTN of statement 266.

Maximum error:

This factor is introduced by LBL D (statement 283) which is none other than the assignment of the error ϵ in Ros in accordance with the assignment of PGM 08 D in the library. From experience it can be seen that repetition of the error coefficient for each calculation sequence constitutes a constraint, and that setting it at 0.01 in the absence of error entry, as provided by PGM 08, does not really spare the user from this preoccupation.

The fact is that although the precision required varies from one operator to the next, everyone generally uses a rather constant factor for a series of calculations.

It is thus practical to keep ϵ in the program, even if this means modifying it to the programming mode as soon as the need arises. This is the role of LBL D' (statement 399) where statements 400 thru 410 can contain € up to 1×10^{-10} unless less precision is preferred. It is then sufficient to fill the empty spaces with NOP instructions or simply with zeros after the first significant figure. Since LBL D' calls D at statement 411 but is itself called by C at

statement 129, it is clear that key C finally controls recall, printout and then entry of the maximum error ϵ programmed by the operator.

Calculation of roots:

The heart of this calculation is PGM 08 E from the library which we call at statements 292 and 309. Determination of the successive roots is implemented by our LBL E (statement 291). From the second root, the lower boundary a takes the value of the preceding root augmented by a minimum quantity equal to $\epsilon \times 10$. This augmentation is an artifice designed to move the calculator off the solution it has just found.

The process continues up to unsuccessful exploration of the last interval. At printout this initiates the characteristic series of 9.999...? provided by the manufacturer's PGM 08. LBL E itself is controlled by LBL C at statement 130. This is why key C in fact initiates determination of the roots at the right time.

Tables of values of x and P(x):

These two tables are successively printed out by LBL C' (statement 323) which samples thirty-nine suitable stored values of x from registers R_{21} thru R_{59} and replaces them immediately in the same registers with the thirty-nine corresponding values of P(x). The median of x may be very close to zero. This means that the median of P(x) corresponds to the value of the polynomial for x = 0 when P(x) = P(-x).

The sequence C' starts with restoration of the lower boundary a in R_{01} and stores a new increment in R_{03} taken from forty statements between a and b. An automatic listing of the memories with loop and error-indicator control provides indexing of the values.

Sequence C' is itself controlled by LBL E at statement 320 after FLAG 07 has used the error signal from the end of root determination. Given that LBL E is subordinate to LBL C, as was stated earlier, sequence C' is finally implemented by key C also. Given the partition used, the thirty-nine sample values of x and then of P(x) occupy statements 480 thru 959. Those of P(x) can be recorded on a magnetic card in groups 3 and 4 for automatic printout by points of the function curve. The polynomials derived from P(x) could obviously be recorded in the same manner.

Calculation of derived polynomials:

The derivation of each polynomial term of the general expression ax" gives a term of the expression anx" ¹. The calculation is performed by LBL B' (statement 414) which, by depressing key B' once, prints out all the coefficients from x° to x° . The sequence has been designed to provide P'(x) from P(x), P"(x) from P'(x) and so forth as long as the polynomial remains differentiable. Since the program then divides the polynomial by its first nonzero coefficient, it will come as no surprise to find a derivative divided by this term. This in no way changes the final results.

As soon as key B' has played its role, it is sufficient to depress key C for the derived polynomial to be handled in accordance with the same complete cycle as described for the initial polynomial. No other intervention is necessary, unless it is desired to return to the initial

polynomial to evaluate it as a function of the roots found for the derived polynomials. This determination is only made after all the derived polynomials that are deemed useful have been used in sequence by the automatic procedure just indicated.

When the coefficients of the initial polynomial have been reentered from R_{16} to R_{10} as at the beginning, enter each root on the keyboard, and each time depress A'. This evaluates the corresponding P(x). The function curve is then completed by virtue of the geometric significance of the derivative by the following coordinates:

- to the root of P'(x) = 0 taken as the abscissa corresponds an ordinate by P(x) which defines a maximum or minimum of P(x) = 0
- to the root of P"(x) = 0 taken as the abscissa corresponds an ordinate by P(x) which defines a point of inflection of P(x) = 0 if there is one

Program of Function Curve

Principle:

The curve of the polynomial is automatically plotted as shown in the program in listing 2. It was necessary to conceive an algorithm that compensates for the relative weakness of the TI-59 in this area, since it accepts only twenty whole positive values on a 2.5 inch tape.

With the exception of special cases, the spacing of the plotted points is manifestly insufficient. It can be seen that to cover an 8.5 by 14 inch sheet of paper (a standard European A4 sheet, 21 by 29.7 cm), six strips of machine

Listing 2: Listing of the program that will plot the function curve.

073 074 075 076 077 076 077 079 080 081 082 083 090 091 092 099 100 097 099 100 101 102 103	000 001 002 003 004 005 005 005 005 005 005 005 005 005
09 9 42 STD 09 02 2 01 2 STD 00 00 53 RC* 00 00 55 + 03 03 43 RCL 03 03 44 RCL 03 03 54 PCL 03 03 55 + 43 RCL 04 03 05 + 43 RCL 04 03 05 + 07 07 55 + 43 RCL 04 03 05 04 07 07 08 03 08 04 09 05 09 05 09 00 00 00 00 00 00 00 00 00 00 00 00	98 ADV 69 DP 60 DP 6
178: 179: 180: 181: 184: 185: 186: 187: 188: 189: 190: 191: 192: 193: 194: 199: 199: 200: 201: 202: 204: 205: 206: 207: 208: 209:	1056 1067 1078 1099 1110 1114 1115 1117 1118 1121 1123 1124 1121 1123 1124 1129 1129 1129 1129 1129 1129 1129
32 XIT 73 RC* 70 00 71 SBR 75 - 90 20 97 DS2 99 DS2 99 ADV 98 ADV 97 DS2 05 05 01 01 49 PRT 69 DP 00 07 05 5 00 00 0	6) + (LC7+LC8) = **0 OP 0019NBLE (LC7+LC8) + 6 + LC3 = D6 6 STD5 OP 21 CD 22 STD0 24 STD0 25 S
001 020 038 047 053 067 072 127 201 220 243 250 269	011234567890123345678901233456789001233456789001234567890 222222222222222222222222222222222222
98 ADV 28 LDG 75 A 112 B 13 C D 14 D 15 E 99 FRT 36 PGM 10 D	00 00 00 00 00 00 00 00 00 00 00 00 00

paper must be juxtaposed. In practice, this means making the data positive, preparing a suitable format and then dividing it into six parts. Thus, the calculator can sequentially print the asterisks corresponding to the thirty-nine values of registers R21 thru R59. This can be accomplished in six runs.

Since asterisks will be printed for only thirty-nine pieces of data on 39 by 6 runs, a printout arrangement by points on the base line is used to mark the nonoperation. The interval between points is equal to the increment of the table of the values of x.

Location in the plane is completed by two other arrangements:

- a sign in the shape of a triangle, in place of a point, marks the middle of the base line when there is no value on the zero abscissa
- the ordinates are marked laterally by a column of points with twenty per tape

Initialization and data entry:

These operations are performed by LBL A (statement 047) and LBL B (statement 053). The lower data item entered first is stored in register Roy, and the upper data item, entered second, is stored in register Ros. The choice of these values determines the amplitude of the graphic reproduction. If it is desired to cover a maximum field, it is necessary to determine the extremes of the values to be reproduced by concurrently consulting the table of the values of P(x) and the group of values of P(x) for x taken from the roots of P'(x) = 0.

Note that LBL B continues (statement 057) with the ad-

dition of the tenth of each value entered. This automatically provides a margin for the sheet.

Service labels:

Since there is no point in spreading signs on a page without identification, a certain number of sequences permit projections along the abscissa and ordinates. LBL ADV (statement 001) prints one point on the base line of the strip when no data appears on the corresponding abscissa. You will recognize the alphanumeric code controlled by instructions OP 00, OP 01 and OP 05.

Instead of a point, LBL PRT (statement 201) prints a small triangle in the middle of the base line. This distinctive sign marks the zero abscissa when no data item corresponds to it. This median is recognized by monitoring register R40 in passing and, by subtracting its ordinal number, it checks for the zero condition using the T register (= t or \neq t). The conditional transfer is executed by means of the LBL = instruction at statement 220 and LBL PGM at statement 243 (the first being called as a subroutine at statement 043 by the LBL - instruction and the second at statement 232 by the LBL =instruction). Naturally, the T register is restored to its previous value immediately after statement 234 and before returning to the main program to serve in the test of the upper limit for the following data item.

Incidentally, it can be observed here that the user is dealing with a structure with four levels of subroutines $(main\ program \rightarrow SBR - \rightarrow SBR = \rightarrow SBR\ PGM \rightarrow SBR$ PRT). The calculator can handle them with no difficulty, since it can accept up to six successive calls. The ordinate location is provided by LBL E' (statement 250), called at

statement 181, which prints a column of points at the end of the tape. For reasons of economy, the alphanumeric characters are grouped in LBL D' at statement 269 and recalled as a subroutine whenever needed.

Data printout:

LBL LOG (statement 020) prints an asterisk when the value of R*00 recalled by indirect addressing is between the lower and upper limits of the tape considered. Printout uses a special instruction OP 07. Conditional transfer is provided by LBL - which transfers execution to LBL LOG if the data item is acceptable after subtracting the value of the lower limit stored in register R20. Finally, the data item processed is excluded from the printing field by addition of the group of seven instructions of the tape format contained in register Rob (statements 029 thru 035).

Data conversion:

This operation is executed by LBL D (statement 072). It assigns the thirty-nine data items collected by recording in groups 3 and 4 of registers R21 thru R59 on completion of calculation of the initial P(x) polynomial. However, this could just as well be a polynomial derived for another calculation purpose. The positive value and formatting of this data for printout are obtained with a better spread by dividing them by the increment of the table of values of x contained in register Ros. Each converted data item replaces the previous data item term for term in the same register R21 thru R59.

Tape printout:

Printout of the six tapes is controlled by LBL E (statement 127). This sequence begins with calculation of the tape format stored in register Ros. Tape indexing depends on register Ros, initially loaded with zero at statement 146, then incremented at statement 166 and printed at statement 173. The lower tape limit is calculated at statement 165 (STO 20) and the upper limit at statement 177 for loading in the T register.

Transfer to the test of the upper tape limit is executed by instruction SBR — at statement 181. The mechanism of LBL E uses a double loop:

- 149 thru 198 for register Roo for data counting load-
- 179 thru 185 for register Ros for tape counting loaded at 6

The entire system is actuated by simply depressing key C, since LBL C at statement 067 monitors D and E. Part 2 of this article will discuss the numerical applications of this program. Samples will be provided to illustrate the initialization and plotting procedures to be followed to output the function curve.

Glossary

Lagrange's method: Several theorems exist that can solve for the real root(s) of a polynomial equation by means of successive approximations. Lagrange's method obtains the real root using only integer calculations, thereby eliminating any roundoff error. This process is therefore very useful for separation of roots located in a small interval.